

Heuristic Based Induction of Answer Set Programs: From Default Theories to Combinatorial problems

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Agenda

- ▶ ILP Problem Definition
- ▶ FOLD Algorithm
- ▶ ILP Problem Definition Revisited (1)
- ▶ Heuristic-based Non-Observation Learning
- ▶ ILP Problem Definition Revisited (2)
- ▶ Induction of ASP programs
- ▶ Applications

ILP Problem Definition

Given

- ▶ Target predicate t , target ground predicates E^+ and E^- ,
Horn background knowledge B with no even cycles

Find hypothesis H such that:

- ▶ $\forall e \in E^+ : B \cup H \models e$
- ▶ $\forall e \in E^- : B \cup H \not\models e$
- ▶ B and H are consistent

In This Paper: A Heuristic-based algorithm to relax the following limitations

- ▶ Only Target Ground Predicates in E^+ , $E^- \implies$
Non-Observation Predicate Learning
- ▶ Horn BK \implies Learning ASP programs

Negation-As-Failure Semantics (NAF)

- ▶ NAF is essential in common sense reasoning (e.g., default reasoning, incomplete knowledge)
- ▶ **Even cycles** (i.e., even number of **not** until reaching the same predicate) are responsible for generating multiple stable models in presence of NAF semantics
- ▶ **Example:**
p :- not q.
q :- not p.
- ▶ Once NAF is allowed in ILP, algorithm should be able to handle ASP programs with multiple *stable models*

Motivation

- ▶ Learning ASP is not a new problem
- ▶ Why a Heuristic-based Algorithm?
 - ▶ Greedy search vs. Exhaustive search (Scalability)
 - ▶ Noise tolerance (Over-fitting)
- ▶ We extend FOIL algorithm (R.Quinlan 90) to induce Answer Set Programs with multiple Stable Models
- ▶ FOLD (**F**irst **O**rders **L**earner of **D**efault-theories) is introduced to learn default theories with one stable model
- ▶ We then extend it to multiple generate/handle multiple stable models

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- ▶ **FOLD Algorithm**
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FOLD algorithm

FOLD algorithm extends FOIL while learning default and possibly multiple exceptions for a concept.

First Order Learner of Default-theories (FOLD)

- ▶ Specialize $target(V_1, \dots, V_m) :- true$ only by adding positive literals
- ▶ Stop once **information gain** turns 0 or the *Maximum Description Length* reached (whichever happens first) save current literals p_1, \dots, p_k
- ▶ Switch the current positive and negative examples
- ▶ recursively call FOLD to learn a predicate called ab
- ▶ Add the following rule to the current hypothesis $target(V_1, \dots, V_m) :- p_1, \dots, p_k, \mathbf{not} ab(V_1, \dots, V_m)$

FOLD Step by Step

fly(X) :- ?

Example

\mathcal{B} : *bird*(X) \leftarrow *penguin*(X).

bird(tweety).

cat(kitty).

\mathcal{E}^+ : *fly*(tweety).

\mathcal{E}^- : *fly*(polly).

bird(woody).

penguin(polly).

fly(woody).

fly(kitty).

List of candidate predicates:

bird(X), *cat*(X), *penguin*(X)

Initially...

fly(X) \leftarrow true. $\mathcal{E}^+ = [\text{tweety, woody}]$ $\mathcal{E}^- = [\text{polly, kitty}]$

FOLD Step by Step

fly(X) :- ?

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\mathcal{B} : *bird(X) ← penguin(X).*

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fly(kitty).

List of candidate predicates:

bird(X), *cat(X)*, *penguin(X)*

Trying...bird(X)

fly(X) ← bird(X) $\mathcal{E}^+ = [\text{tweety,woody}]$ $\mathcal{E}^- = [\text{polly}]$

FOLD Step by Step

fly(X) :- ?

Example

\mathcal{B} : *bird*(X) \leftarrow *penguin*(X).

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fly(woody).

fly(kitty).

List of candidate predicates:

bird(X), *cat*(X), *penguin*(X)

Trying...*cat*(X)

fly(X) \leftarrow *cat*(X) $\mathcal{E}^+ = []$ $\mathcal{E}^- = [\text{kitty}]$

FOLD Step by Step

fly(X) :- ?

Example

\mathcal{B} : *bird*(X) \leftarrow *penguin*(X).

bird(tweety).

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\mathcal{E}^+ : *fly*(tweety).

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List of candidate predicates:

bird(X), *cat*(X), *penguin*(X)

Trying...*penguin*(X)

fly(X) \leftarrow *penguin*(X) $\mathcal{E}^+ = []$ $\mathcal{E}^- = [\text{polly}]$

FOLD Step by Step

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bird(woody).

penguin(polly).

fly(woody).

fly(kitty).

After first iteration

fly(X) \leftarrow *bird*(X). $\mathcal{E}^+ = [\text{tweety,woody}]$ $\mathcal{E}^- = [\text{polly}]$

FOLD Step by Step

fly(X) :- ?

Example

\mathcal{B} : *bird(X) ← penguin(X).*

bird(tweety).

bird(woody).

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\mathcal{E}^+ : *fly(tweety).*

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fly(kitty).

information gain turns 0...

fly(X) ← bird(X). $E^+ = [\text{tweety,woody}]$ $E^- = [\text{polly}]$

FOLD Step by Step

fly(X) :- ?

Example

\mathcal{B} : *bird*(X) \leftarrow *penguin*(X).

bird(tweety).

cat(kitty).

\mathcal{E}^+ : *fly*(tweety).

\mathcal{E}^- : *fly*(polly).

bird(woody).

penguin(polly).

fly(woody).

fly(kitty).

At this point, FOLD swaps $E^+ = [\text{tweety,woody}]$ and $E^- = [\text{polly}]$ and recursively calls FOLD

Initially

ab(X) \leftarrow true. $E^+ = [\text{polly}]$ $E^- = [\text{tweety,woody}]$

FOLD Step by Step

fly(X) :- ?

Example

\mathcal{B} : *bird(X) ← penguin(X).*

bird(tweety).

cat(kitty).

\mathcal{E}^+ : *fly(tweety).*

\mathcal{E}^- : *fly(polly).*

bird(woody).

penguin(polly).

fly(woody).

fly(kitty).

After first iteration

ab(X) ← penguin(X). $E^+ = [\text{polly}]$ $E^- = []$

FOLD Step by Step

fly(X) :- ?

Example

\mathcal{B} : *bird(X) ← penguin(X).*

bird(tweety).

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Since no negative example left, recursive call returns. The original call to FOLD returns with the following default theory:

fly(X) :- bird(X), not ab(X).

ab(X) :- penguin(X).

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- ▶ **ILP Problem Definition Revisited (1)**
- ▶ Heuristic-based Non-Observation Learning
- ▶ ILP Problem Definition Revisited (2)
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ILP Problem Definition (Revisited)

Given

- ▶ Target predicate t , target ground predicates E^+ and E^- ,
Horn background knowledge B with no even cycles

Find hypothesis H such that:

- ▶ $\forall e \in E^+ : B \cup H \models e$
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Non-Observation Predicate Learning**
2. **Horn BK \implies Learning ASP programs**

Non-Observation Predicate Learning

- ▶ Allows to have examples other than the ground target predicate
- ▶ These non-target examples impact the hypothesis indirectly
- ▶ **Example:** Learning target = $r(X)$ with $E^+ = \{p(a), r(c)\}$, $E^- = \{p(d)\}$

(1) $p(X) :- s(X), \text{ not } r(X).$

(2) $s(X) :- q(X,Y), r(Y).$

(3) $q(a,b).$

(4) $s(d).$

- ▶ $H \models p(a)$ requires: $H \models s(a), H \not\models r(a)$
- ▶ $s(a)$ requires: $r(b)$
- ▶ $H \not\models p(d)$ requires: $H \not\models r(d)$

Abduction in Goal-Directed ASP

- ▶ Non-OPL is realized via $s(\text{ASP})$, a Goal-Directed ASP system
 - ▶ Takes an ASP program and a query Q
 - ▶ enumerates all answer sets that contain propositions/predicates of Q
 - ▶ Enumeration employs co-inductive SLD resolution to systematically compute the elements of the Greatest Fix-Point (GFP) of P .
 - ▶ It outputs “partial answer sets” that contain only elements necessary to establish Q .
 - ▶ $s(\text{ASP})$ does not ground the ASP program
- ▶ $s(\text{ASP})$ allows to run a query Q abductively
- ▶ Whenever needed, Q succeeds by assuming facts from a set defined of $\#$ abducibles

Abduction in Goal-Directed ASP (2)

- ▶ Non-OPL is realized via $s(\text{ASP})$, a Goal-Directed ASP system
 - ▶ Takes an ASP program and a query Q
 - ▶ enumerates all answer sets that contain propositions/predicates of Q
 - ▶ Enumeration employs co-inductive SLD resolution to systematically compute the elements of the Greatest Fix-Point (GFP) of P .
 - ▶ It outputs “partial answer sets” that contain only elements necessary to establish Q .
 - ▶ $s(\text{ASP})$ does not ground the ASP program
- ▶ $s(\text{ASP})$ allows to run a query Q abductively
- ▶ Whenever needed, Q succeeds by assuming facts from a set defined of $\#$ abducibles

Abduction in Goal-Directed ASP (3)

Example: Learning target = $r(X)$ with $E^+ = \{p(a), r(c)\}$,
 $E^- = \{p(d)\}$

(1) $p(X) :- s(X), \text{not } r(X).$

(2) $s(X) :- q(X,Y), r(Y).$

(3) $q(a,b).$

(4) $s(d).$

We Run s(ASP) System and define #abducible $r(x)$

▶ $?- p(a)$

▶ **Partial Answer set** $\{p(a), q(a,b), r(b), s(a), \text{not } r(a)\}$

▶ $?- \text{not } p(d)$

▶ **Partial Answer set** $\{p(d), s(d), r(d)\}$

▶ $E^+ = \{r(c), r(b), r(d)\}$

▶ $E^- = \{r(a)\}$

ILP Problem Definition (Revisited)

Given

- ▶ Target predicate t , target ground predicates E^+ and E^- ,
Horn background knowledge B with no even cycles

Find hypothesis H such that:

- ▶ $\forall e \in E^+ : B \cup H \models e$
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Induction of ASP Programs with Multiple Stable Models

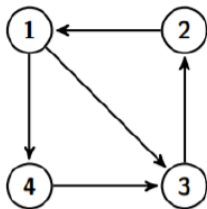
- ▶ $B \cup H$ has multiple stable models
- ▶ Examples $e \in E^+$ hold only in some of the stable models of $B \cup H$
- ▶ We adopt the ILASP¹ *partial interpretation* as the ILP framework to induce programs with multiple stable models

¹M. Law, A. Russo, K. Broda, Inductive Learning of Answer Set Programs, Logics in Artificial Intelligence, Springer, 2014

Induction of ASP Programs with Multiple Stable Models

Definition A partial interpretation E is a pair $E = \langle E^{inc}, E^{exc} \rangle$ of sets of ground atoms called inclusions and exclusions, respectively. Let $A \in AS(B \cup H)$ denote a stable model of $B \cup H$. A extends $\langle E^{inc}, E^{exc} \rangle$ if and only if $(E^{inc} \subseteq A) \wedge (E^{exc} \cap A = \emptyset)$

Example: The graph-coloring problem



– Positive examples:

$$E_1^+ = \{ \langle r(1), b(2), g(3), b(4) \rangle, \langle \text{not } b(1), \text{not } g(1), \text{not } r(2), \text{not } g(2), \text{not } r(3), \text{not } b(3), \text{not } r(4), \text{not } g(4) \rangle \}$$

$$E_2^+ = \{ \langle b(1), r(2), g(3), r(4) \rangle, \langle \text{not } r(1), \text{not } g(1), \text{not } b(2), \text{not } g(2), \text{not } r(3), \text{not } b(3), \text{not } b(4), \text{not } g(4) \rangle \}$$

– Negative examples:

$$E_1^- = \{ \langle r(1) \rangle, \langle \text{not } r(2) \rangle \} \quad E_2^- = \{ \langle r(1) \rangle, \langle \text{not } r(3) \rangle \}$$

ILP Problem Definition Revisited

Given

- ▶ Target predicate t
- ▶ Two sets of **partial interpretations** E^+ and E^-
- ▶ **ASP** background knowledge B

Find hypothesis H such that:

- ▶ $\forall e^+ \in E^+ \exists A \in AS(B \cup H)$ such that A extends e^+
- ▶ $\forall e^- \in E^- \nexists A \in AS(B \cup H)$ such that A extends e^-

FOLD algorithm is extended to solve instances of this problem

Example - “Who goes to the party?”

Background Knowledge

conflict(X,Y) :- conflict(Y,X).

:- person(X), works(X), off(X).

person(p1). person(p2). person(p3). person(p4). person(p5).

conflict(p1,p4).

conflict(p2,p3).

Target Predicate: goesToParty(X) :- ?

Positive Examples

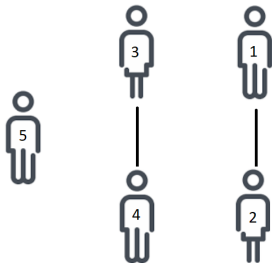
$E_1^+ = \{ \langle g(p1),g(p2),o(p1),o(p2),w(p3),o(p4),w(p5) \rangle, \langle g(p3),g(p4),g(p5) \rangle \}$

$E_2^+ = \{ \langle g(p3),g(p4),g(p5),o(p1),o(p2),o(p3),o(p4),o(p5) \rangle, \langle g(p1),g(p2) \rangle \}$

$E_3^+ = \{ \langle g(p1),g(p3),g(p5),o(p1),o(p2),o(p3),w(p4),o(p5) \rangle, \langle g(p2),g(p4) \rangle \}$

$E_4^+ = \{ \langle g(p2),g(p5),w(p1),o(p2),w(p3),w(p4),o(p5) \rangle, \langle g(p1),g(p3),g(p4) \rangle \}$

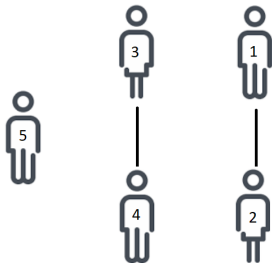
Example - "Who goes to the party?"


$$E_1^+ = \{ \langle g(p1), g(p2), o(p1), o(p2), w(p3), o(p4), w(p5) \rangle, \langle g(p3), g(p4), g(p5) \rangle \}$$
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Trying...

```
goesToParty(X) :- true.
```

Example - "Who goes to the party?"



$$E_1^+ = \{ \langle g(p1), g(p2), o(p1), o(p2), w(p3), o(p4), w(p5) \rangle, \langle g(p3), g(p4), g(p5) \rangle \}$$

$$E_2^+ = \{ \langle g(p3), g(p4), g(p5), o(p1), o(p2), o(p3), o(p4), o(p5) \rangle, \langle \cancel{g(p1)}, \cancel{g(p2)} \rangle \}$$

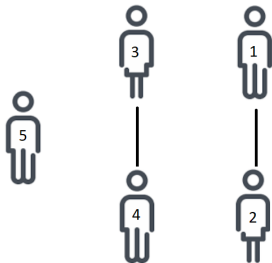
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$$E_4^+ = \{ \langle g(p2), g(p5), w(p1), o(p2), w(p3), w(p4), o(p5) \rangle, \langle \cancel{g(p1)}, \cancel{g(p3)}, \cancel{g(p4)} \rangle \}$$

Trying... works(X)

goesToParty(X) :- works(X).

Example - "Who goes to the party?"



$$E_1^+ = \{ \langle \text{g}(p1), \text{g}(p2), \text{o}(p1), \text{o}(p2), \text{w}(p3), \text{o}(p4), \text{w}(p5) \rangle, \langle \text{g}(p3), \text{g}(p4), \text{g}(p5) \rangle \}$$

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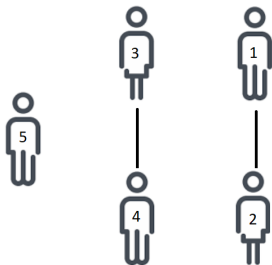
$$E_3^+ = \{ \langle \text{g}(p1), \text{g}(p3), \text{g}(p5), \text{o}(p1), \text{o}(p2), \text{o}(p3), \text{w}(p4), \text{o}(p5) \rangle, \langle \text{g}(p2), \text{g}(p4) \rangle \}$$

$$E_4^+ = \{ \langle \text{g}(p2), \text{g}(p5), \text{w}(p1), \text{o}(p2), \text{w}(p3), \text{w}(p4), \text{o}(p5) \rangle, \langle \text{g}(p1), \text{g}(p3), \text{g}(p4) \rangle \}$$

Trying... off(X)

```
goesToParty(X) :- off(X).
```

Example - "Who goes to the party?"



$$E_1^+ = \{ \langle \text{g}(p1), \text{g}(p2), \text{o}(p1), \text{o}(p2), \text{w}(p3), \text{o}(p4), \text{w}(p5) \rangle, \langle \text{g}(p3), \text{g}(p4), \text{g}(p5) \rangle \}$$

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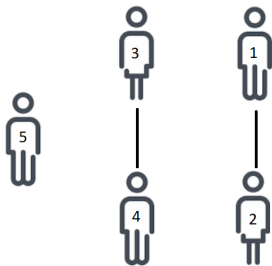
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After 1st iteration

```
goesToParty(X) :- off(X).
```


Example - "Who goes to the party?"



$E_1^+ = \{ \langle g(p1), g(p2), o(p1), o(p2), w(p3), o(p4), w(p5) \rangle, \langle g(p3), g(p4), g(p5) \rangle \}$

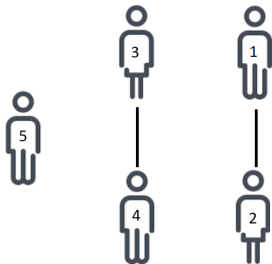
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After 1st iteration

`goesToParty(X) :- off(X).`

Example - "Who goes to the party?"



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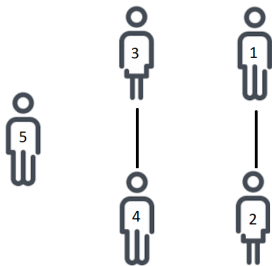
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No more gainful candidate predicate, Swapping E^{inc}, E^{exc}

`goesToParty(X) :- off(X)`

Example - "Who goes to the party?"



$$E_1^+ = \{ \langle -g(p4), g(p1), g(p2), o(p1), o(p2), w(p3), o(p4), w(p5) \rangle, \langle -g(p1), -g(p2) \rangle \}$$

$$E_2^+ = \{ \langle -g(p1), -g(p2), g(p3), g(p4), g(p5), o(p1), o(p2), o(p3), o(p4), o(p5) \rangle, \langle -g(p3), -g(p4), -g(p5) \rangle \}$$

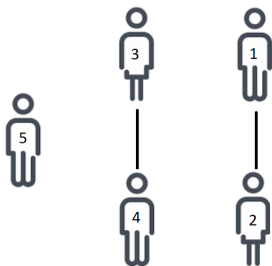
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Learn `-goesToParty(X)`

```
goesToParty(X) :- off(X), not -goesToParty(X)
```

```
-goesToParty(X) :- true.
```

Example - "Who goes to the party?"



$$E_1^+ = \{ \langle g(p1), g(p2), o(p1), o(p2), w(p3), o(p4), w(p5) \rangle, \langle -g(p1), -g(p2) \rangle \}$$

$$E_2^+ = \{ \langle g(p3), g(p4), g(p5), o(p1), o(p2), o(p3), o(p4), o(p5) \rangle, \langle -g(p3), -g(p4), -g(p5) \rangle \}$$

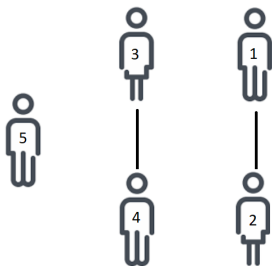
$$E_3^+ = \{ \langle g(p1), g(p3), g(p5), o(p1), o(p2), o(p3), w(p4), o(p5) \rangle, \langle -g(p1), -g(p2) \rangle \}$$

Trying... conflict(X,Y)

```
goesToParty(X) :- off(X), not -goesToParty(X)
```

```
-goesToParty(X) :- conflict(X,Y),
```

Example - "Who goes to the party?"

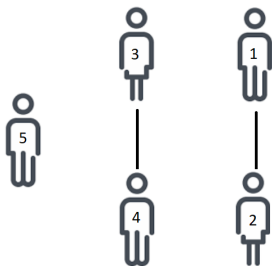

$$E_1^+ = \{ \langle g(p1), g(p2), o(p1), o(p2), w(p3), o(p4), w(p5) \rangle, \langle \rangle \}$$
$$E_2^+ = \{ \langle g(p3), g(p4), g(p5), o(p1), o(p2), o(p3), o(p4), o(p5) \rangle, \langle \rangle \}$$
$$E_3^+ = \{ \langle g(p1), g(p3), g(p5), o(p1), o(p2), o(p3), w(p4), o(p5) \rangle, \langle \rangle \}$$

Trying... goesToParty(Y)

```
goesToParty(X) :- off(X), not -goesToParty(X)
```

```
-goesToParty(X) :- conflict(X,Y), goesToParty(Y)
```

Example - "Who goes to the party?"



$E_1^+ = \{ \langle g(p1), g(p2), o(p1), o(p2), w(p3), o(p4), w(p5) \rangle, \langle \rangle \}$

$E_2^+ = \{ \langle g(p3), g(p4), g(p5), o(p1), o(p2), o(p3), o(p4), o(p5) \rangle, \langle \rangle \}$

$E_3^+ = \{ \langle g(p1), g(p3), g(p5), o(p1), o(p2), o(p3), w(p4), o(p5) \rangle, \langle \rangle \}$

Done...

```
goesToParty(X) :- off(X), not -goesToParty(X)
```

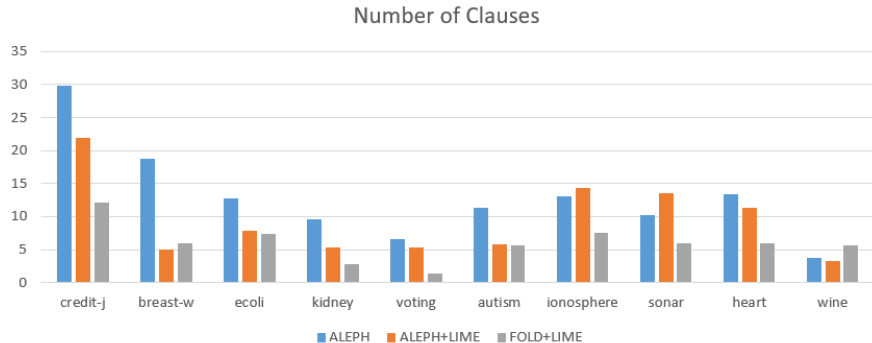
```
-goesToParty(X) :- conflict(X,Y), goesToParty(Y)
```

- ▶ ILP Problem Definition
- ▶ FOLD Algorithm
- ▶ ILP Problem Definition Revisited (1)
- ▶ Heuristic-based Non-Observation Learning
- ▶ ILP Problem Definition Revisited (2)
- ▶ Induction of ASP programs
- ▶ **Applications**

FOLD Algorithm Applications

- ▶ Inductive Learning of Default Theories
- ▶ Learning *generate and test* ASP programs for combinatorial Problems (e.g., Graph Coloring and N-Queen)
 - ▶ *generate* part is learned from positive examples E^+
 - ▶ *test* part is learned from negative examples E^+ , in form of ASP constraints (even loops)
- ▶ **Induction of Non-monotonic Logic Programs to Explain Boosted Tree Models Using LIME**
 - ▶ LIME (**L**ocally **I**nterpret **M**odel-agnostic **E**xplanations) explains complex classifiers decisions
 - ▶ For every training example LIME filters out irrelevant features
 - ▶ FOLD learns very succinct set of clauses from the data set transformed by LIME

FOLD and ALEPH comparison on UCI Standard benchmarks transformed by LIME



²<http://arxiv.org/abs/1808.00629>

Data Set	Algorithm											
	ALEPH				ALEPH+LIME				FOLD+LIME			
	Prec.	Recall	Acc.	F1	Prec.	Recall	Acc.	F1	Prec.	Recall	Acc.	F1
credit-j												
breast-w	92.8	0.87	0.93	0.89	0.98	0.65	0.87	0.76	0.94	0.92	0.95	0.92
ecoli	0.85	0.75	0.84	0.80	0.95	0.84	0.92	0.89	0.95	0.88	0.93	0.91
kidney	0.96	0.92	0.93	0.94	0.99	0.95	0.96	0.97	0.93	0.95	0.93	0.94
voting	0.97	0.94	0.95	0.95	0.98	0.95	0.96	0.96	0.98	0.96	0.97	0.97
autism	0.73	0.43	0.79	0.53	0.88	0.38	0.81	0.52	0.84	0.88	0.91	0.86
ionosphere	0.89	0.87	0.85	0.88	0.92	0.85	0.86	0.88	0.91	0.86	0.86	0.89
sonar	0.74	0.56	0.66	0.64	0.81	0.72	0.74	0.76	0.87	0.75	0.78	0.80
heart	0.76	0.75	0.78	0.75	0.79	0.70	0.79	0.74	0.82	0.74	0.82	0.78
wine	0.94	0.86	0.93	0.89	0.91	0.85	0.92	0.88	0.98	0.85	0.93	0.91

Table 1: Evaluation of ALEPH, ALEPH+LIME and FOLD+LIME on 10 UCI Datasets

³<http://arxiv.org/abs/1808.00629>

Thank you

A large, rounded green square button with a white shadow effect. The text "Q&A" is centered on the button in a white, bold, sans-serif font.

Q&A